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SELECTION OF MIXED SAMPLING PLAN WITH QSS - 3($n; c_N, c_T$) PLAN AS ATTRIBUTE PLAN INDEXED THROUGH MAPD AND LQL

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ABSTRACT

This paper presents the procedure for the construction and selection of the mixed sampling plan using MAPD as a quality standard with the QSS-3 ($n; c_N, c_T$) plan as attribute plan. The plans indexed through MAPD and LQL are constructed and compared for their efficiency. Tables are constructed for easy selection of the plan.

KEYWORDS

limiting quality level, maximum allowable percent defective, operating characteristic, tangent intercept.

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1. INTRODUCTION

Mixed sampling plans consist of two stages of rather different nature. During the first stage the given lot is considered as a sample from the respective production process and a criterion by variables is used to check process quality. If process quality is judged to be sufficiently good, the lot is accepted. Otherwise the second stage of the sampling plan is entered and lot quality is checked directly by means of an attribute sampling plan.

There are two types of mixed sampling plans called independent and dependent plans. If the first stage sample results are not utilized in the second stage, the plan is said to be independent otherwise dependent. The principal advantage of a mixed sampling plan over pure attribute sampling plans is a reduction in sample size for a similar amount of protection.

The second stage attribute inspection becomes more important to discriminate the lot if the first stage variable inspection fails to accept the lot. If rejection occurs during the normal inspection, tightened inspection is recommended in the mixed system and vice versa in the second stage. Hence Quick Switching System is imposed in the second stage to sharpen the sampling situation and to insist the producer to manufacture goods within the Limiting Quality Level. Dodge (1967) proposed a sampling system called a 'Quick Switching System' (QSS) consisting of pairs of normal and tightened plans.

Schilling (1967) proposed a method for determining the operating characteristics of mixed variables – attributes sampling plans, single sided specification and standard deviation known using the normal approximation. Devaarul (2003), Sampath Kumar (2007), Sampath Kumar, et.al (2012a,b,c,d,e,f,g) have made contributions to mixed sampling plans for independent case. QSSs were originally proposed by Dodge (1967) and investigated by Romboski (1969) and Govindaraju (1991). Dodge (1967) proposed a new sampling system consisting of pairs of normal and tightened plans. QSS developed with attributes by Romboski (1969) is a reduction in the sample size required to achieve approximately the same operating characteristic curve.

In this paper, using the operating procedure of mixed sampling plan with QSS-3($n; c_N, c_T$) plan as attribute plan, tables are constructed for the mixed sampling plan indexed through (i) MAPD (ii) LQL (limiting quality level). The plan indexed through MAPD is compared with the plan indexed through LQL. Suitable suggestions are also provided for future research.

2. GLOSSARY OF SYMBOL

The symbols used in this paper are as follows:

- P : submitted quality of lot or process
 $P_a(p)$: probability of acceptance for given quality 'p'
 p_2 : the submitted quality such that $P_a(p_2) = 0.10$ (also called LQL)
 p_a : maximum allowable percent defective (MAPD)
 h : relative slope at 'p.'
 n_1 : sample size of variable sampling plan
 n_2 : sample size of attribute sampling plan
 c_N : acceptance number of normal inspection
 c_T : acceptance number of tightened inspection
 β_1 : probability of acceptance for lot quality 'p'
 β_1' : probability of acceptance assigned to first stage for percent defective 'p'
 β_1'' : probability of acceptance assigned to second stage for percent defective 'p'

- d : observed number of nonconforming units in a sample of n units
- z(j) : 'z' value for the jth ordered observation
- k : variable factor such that a lot is accepted if $\bar{X} \leq A = U - k\sigma$

3. OPERATING PROCEDURE OF MIXED SAMPLING PLAN WITH QSS-3(n;c_N,c_T) AS ATTRIBUTE PLAN

Schilling (1967) has given the following procedure for the independent mixed sampling plan with Upper specification limit (U) and known standard deviation (σ).

- ❖ Determine the parameters of the mixed sampling plan n₁, n₂, k, c_N and c_T.
- ❖ Take a random sample of size n₁ from the lot.

❖ If a sample average $\bar{X} \leq A = U - k\sigma$, accept the lot.

❖ If a sample average $\bar{X} > A = U - k\sigma$, go to step 1.

Step 1: From a lot, take a random sample of size n₂ at the normal level. Count the number of defectives 'd'

- ❖ If d ≤ c_N, accept the lot and repeat step 1.
- ❖ If d > c_N, reject the lot and go to step 2.

Step 2: From the next lot, take a random sample of size n₂ at the tightened level. Count the number of defectives 'd'

- ❖ If d ≤ c_T, accept the lot and continue inspection until three lots in succession are accepted. If so go to step-1 otherwise repeat step-2.
- ❖ If d > c_T, reject the lot and repeat step 2 for the next lot.

4. CONSTRUCTION OF MIXED SAMPLING PLAN HAVING QSS-3(n;c_N,c_T) AS ATTRIBUTE PLAN

The operation of mixed sampling plans can properly be assessed by the OC curve for given values of the fraction defective. The development of mixed sampling plans and the subsequent discussions are limited only to the upper specification limit 'U'. A parallel discussion can be made for lower specification limits.

The procedure for the construction of mixed sampling plans is provided by Schilling (1967) for a given 'n₁' and a point 'p₁' on the OC curve is given below.

- ❖ Assume that the mixed sampling plan is independent
- ❖ Split the probability of acceptance (β₁) determining the probability of acceptance that will be assigned to the first stage. Let it be β₁'.
- ❖ Decide the sample size n₁ (for variable sampling plan) to be used

❖ Calculate the acceptance limit for the variable sampling plan as $A = U - k\sigma = U - [z(p_1) + z$

(β₁') / $\sqrt{n_1}] \sigma$, where U is the upper specification limit and z (t) is the standard normal variate

$$\text{corresponding to 't' such that } t = \int_{z(t)}^{\infty} \frac{1}{\sqrt{2\pi}} e^{-u^2/2} du$$

❖ Determine the sample average \bar{X} . If a sample average $\bar{X} > A = U - k\sigma$, take a second stage sample of size 'n₂' using attribute sampling plan.

❖ Split the probability of acceptance β₁ as β₁' and β₁" , such that β₁ = β₁' + (1 - β₁') β₁". Fix the value of β₁'.

❖ Now determine β₁" , the probability of acceptance assigned to the attributes plan associated with the second stage sample as β₁" = (β₁ - β₁') / (1 - β₁')

❖ Determine the appropriate second stage sample of size 'n₂' from

Pa (p) = β₁" for p = p₁.

Using the above procedure tables can be constructed to facilitate easy selection of mixed sampling plan with QSS-3 (n;c_N,c_T) plan as attribute plan indexed through MAPD and LQL.

According to Soundararajan and Arumainayagam (1988), the operating characteristic function of QSS-3 is given below.

$$P_a(p) = \frac{a b^3 + b(1-a)(1+b+b^2)}{b^3 + (1-a)(1+b+b^2)} \tag{1}$$

$$\text{Where } a = \sum_{i=0}^{c_N} \frac{e^{-n_2 p} (n_2 p)^i}{i!} \tag{2}$$

$$b = \sum_{j=0}^{c_T} \frac{e^{-n_2 p} (n_2 p)^j}{j!} \tag{3}$$

(for acceptance number tightening)

5. CONSTRUCTION OF THE PLANS INDEXED THROUGH MAPD

MAPD (p*), introduced by Mayer (1967) and further studied by Soundararajan (1975) is the quality level corresponding to the inflection point of the OC curve. The degree of sharpness of inspection about this quality level 'p*' is measured by 'p_t', the point at which the tangent to the OC curve at the inflection point cuts

the proportion defective axis. For designing, Soundararajan (1975) proposed a selection procedure for mixed sampling plan indexed with MAPD and $R = \frac{p_t}{p^*}$.

Using the probability mass function of QSS-3, given in expression (1), the inflection point (p*) is obtained by using $\frac{d^2 P_a(p)}{dp^2} = 0$ and $\frac{d^3 P_a(p)}{dp^3} \neq 0$.

The relative slope of the OC curve h* = $\left[\frac{-p}{P_a(p)} \right] \frac{dP_a(p)}{dp}$ at p = p*. The inflection tangent of the OC curve cuts the 'p' axis at

$p_t = p^* + (p^* / h^*)$. The values of n₂p*, h*, n₂p_t and R = p_t/p* are calculated for different values of 'c_N' and 'c_T' for β₁' = 0.04 using c++ program and presented in Table 1.

5.1 SELECTION OF THE PLAN

For the given values of p_0 and p_t , the ratio $R = \frac{p_t}{p_0}$ is found and the nearest value of R is located in Table 1. The corresponding value of c_N , c_T and $n_2 p_0$ values are noted and the value of n_2 is obtained using $n_2 = \frac{n_2 p_0}{p_0}$.

5.2 Example: Given $p_0 = 0.049$, $p_t = 0.060$ and $\beta_1' = 0.04$, the ratio $R = \frac{p_t}{p_0} = 1.2245$. In Table 1, the nearest R value is 1.2259 which is corresponding to $c_N = 9$

and $c_T = 4$. The value of $n_2 p_0 = 5.7586$ is found and hence the value of n_2 is determined as $n_2 = \frac{5.7586}{0.049} = 118$. Thus $n_2 = 118$, $c_N = 9$ and $c_T = 4$ are the parameters selected for the mixed sampling plan having QSS-3($n_2; c_N, c_T$) as attribute plan using Poisson Distribution as a baseline distribution, for the given values of $p_0 = 0.049$ and $p_t = 0.060$.

6. CONSTRUCTION OF MIXED SAMPLING PLAN INDEXED THROUGH LQL

The procedure given in Section 5 is used for constructing the mixed sampling plan indexed through LQL (p_2). By assuming the probability of acceptance of the lot be $\beta_2 = 0.10$ and $\beta_2' = 0.04$, the $n_2 p_2$ values are calculated for different values of ' c_N ' and ' c_T ' using c++ program and is presented in Table 1.

6.1 SELECTION OF THE PLAN

Table 1 is used to construct the plans when LQL (p_2), ' c_N ' and ' c_T ' are given. For any given values of p_2 , ' c_N ' and ' c_T ' one can determine n_2 value using $n_2 = \frac{n_2 p_2}{p_2}$.

TABLE 1: VARIOUS CHARACTERISTICS OF THE MIXED SAMPLING PLAN WHEN $\beta_1' = \beta_2' = 0.04$ and $\beta_2 = 0.10$

c_N	c_T	$n_2 p_2$	β_2''	$n_2 p_0$	h_0	$n_2 p_t$	$R = p_t/p_0$
3	0	2.7800	0.8851	0.8484	0.6327	2.1893	2.5805
10	0	3.4557	0.9579	2.3603	0.6691	5.8879	2.4946
1	0	2.7733	0.7210	0.5622	0.6814	1.3873	2.4676
7	1	4.5122	0.9335	2.3060	0.7024	5.5890	2.4237
8	1	4.5520	0.9320	2.5918	0.8221	5.7445	2.2164
4	0	2.7907	0.8671	1.1161	0.9356	2.3090	2.0688
2	1	4.4727	0.6864	1.3996	0.9514	2.8707	2.0511
3	1	4.4740	0.6575	1.7212	1.4628	2.8978	1.9810
2	2	5.9879	0.5888	2.3273	1.0443	4.5559	1.9576
11	1	4.8771	0.9296	3.4169	1.1736	6.3284	1.8521
3	3	7.4157	0.5880	3.2653	1.2304	5.9192	1.8128
5	1	4.4817	0.8131	2.0155	1.4064	3.4486	1.7110
4	7	12.7172	0.5269	7.1940	1.5623	11.7987	1.6401
4	2	5.9895	0.6501	2.6194	1.6358	4.2207	1.6113
5	2	5.9914	0.6319	2.9340	2.1926	4.2721	1.4561
7	6	11.4327	0.5168	6.7153	2.2990	9.6363	1.4350
6	4	8.7904	0.5477	4.8066	2.2988	6.8975	1.4350
6	3	7.4186	0.6304	3.8544	2.3165	5.5183	1.4317
8	2	6.0127	0.7713	3.5357	2.4985	4.9508	1.4002
8	9	15.2374	0.4536	9.9518	2.5607	13.8382	1.3905
8	6	11.4334	0.4906	7.0321	2.8004	9.5432	1.3571
9	1	4.6228	0.7919	3.1488	2.8167	4.2491	1.3494
9	2	6.0342	0.7680	3.8334	2.8993	5.1556	1.3449
7	4	8.7917	0.5228	5.1245	2.9059	6.8880	1.3441
7	3	7.4213	0.6156	4.1706	2.9215	5.5982	1.3423
10	2	6.0732	0.7653	4.1257	3.3045	5.3742	1.3026
10	6	11.4362	0.4343	7.6803	4.0597	9.5721	1.2463
9	3	7.4338	0.5867	4.7917	4.3420	5.8953	1.2303
9	4	8.7976	0.4720	5.7586	4.4269	7.0594	1.2259
10	4	8.8036	0.4478	6.0709	5.3391	7.2080	1.1873
11	4	8.8137	0.4250	6.3795	6.3485	7.3844	1.1575

6.2 Example: Given $p_2 = 0.07$, $c_N = 9$ and $c_T = 4$ and $\beta_2' = 0.04$. Using Table 1, find $n_2 = \frac{n_2 p_2}{p_2} = \frac{8.7976}{0.07} = 126$. Thus $n_2 = 126$, $c_N = 9$ and $c_T = 4$ are the parameters selected for the mixed sampling plan having QSS-3($n_2; c_N, c_T$) as attribute plan for a specified $p_2 = 0.07$, $c_N = 9$ and $c_T = 4$.

7. COMPARISON OF MIXED SAMPLING PLAN INDEXED THROUGH MAPD AND LQL

In this section mixed sampling plan indexed through MAPD is compared with mixed sampling plan indexed through LQL by fixing the parameters c_N , c_T and β_1' . For the specified values of p_0 and p_t with the assumption $\beta_1' = 0.04$, one can find the values of c_N , c_T and n_2 indexed through MAPD. By fixing the values of c_N and

c_T , find the value of p_2 by equating $Pa(p) = \beta_2 = 0.10$. Using $\beta_2' = 0.04$, c_N and c_T one can find the value of n_2 using $n_2 = \frac{n_2 p_0}{p_0}$ from Table 1. For different combinations of p_0 , p_t , c_N and c_T the values of n_2 (indexed through MAPD) and n_2 (indexed through LQL) are calculated and presented in Table 2.

TABLE 2: COMPARISON OF PLANS INDEXED THROUGH MAPD AND LQL

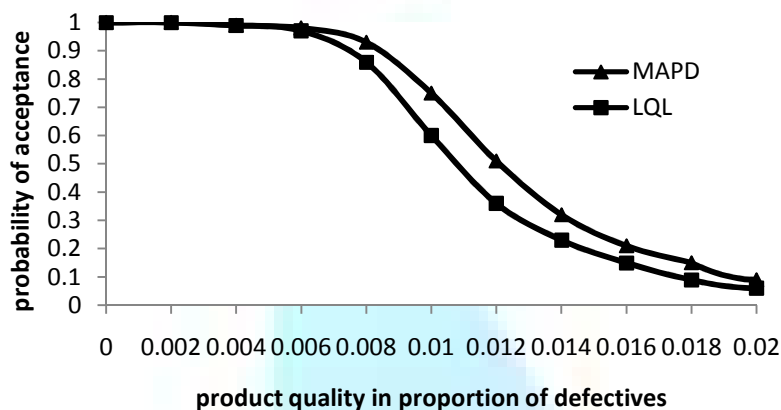
p*	p _t	C _N	C _T	INDEXED THROUGH MAPD	INDEXED THROUGH LQL
				n ₂	n ₂
0.011*	0.016	5	2	267	300
0.025	0.035	8	2	141	157
0.059	0.068	11	4	108	118
0.063	0.085	9	1	50	54

*OC Curve is drawn

7.1 CONSTRUCTION OF OC CURVE

The OC curves for the plans n₂ = 267, C_N = 5, C_T = 2 (indexed through MAPD) and n₂ = 300, C_N = 5, C_T = 2 (indexed through LQL) based on the different values of n₂p₀ and p₀(p) are presented in Figure 1.

FIGURE 1: OC CURVES FOR QSS-2(267;5,2) AND (300;5,2)



8. CONCLUSION

In this paper, using the operating procedure of mixed sampling plan with QSS-3(n;C_N,C_T) as attribute plan, tables are constructed for the mixed sampling plan indexed through the parameters MAPD and LQL by taking Poisson distribution as a baseline distribution. It is concluded from the study that the second stage sample size required for QSS-3(n;C_N,C_T) plan indexed through MAPD is less than that of the second stage sample size of the QSS-3(n;C_N,C_T) plan indexed through LQL. Examples are provided for a specified value of β₁' = 0.04. If the floor engineers know the levels of MAPD or LQL, they can have their sampling plans on the floor itself by referring to the tables. This provides the flexibility to the floor engineers in deciding their sampling plans. Various plans can also be constructed to make the system user friendly by changing the first stage probabilities (β₁', β₂') and can also be compared for their efficiency.

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